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Stochastic theory of nonlinear auto-oscillator: Spin-torque nano-oscillator

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Outline



Introduction

- Linear and nonlinear auto-oscillators
- Spin-torque oscillator (STO)
- Stochastic model of a nonlinear auto-oscillator
- Generation linewidth of a nonlinear auto-oscillator
 - Theoretical results
 - Comparison with experiment (STO)
- Summary

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Models of (weakly perturbed) auto-oscillators



Auto-oscillator – autonomous dynamical system with stable limit cycle

• Phase model

Unperturbed system:

$$\frac{d\mathbf{x}}{dt} = \mathbf{F}(\mathbf{x}) \qquad \mathbf{x} = \mathbf{X}_0(\omega_0 t + \phi_0) \qquad \mathbf{X}_0(\phi + 2\pi) = \mathbf{X}_0(\phi)$$

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Perturbed system:

$$\frac{d\mathbf{x}}{dt} = \mathbf{F}(\mathbf{x}) + \mathbf{f}(t, \mathbf{x}) \qquad \mathbf{x} = \mathbf{X}_0(\phi(t)) + \mathbf{y}(t)$$

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$$\frac{d\phi}{dt} - \omega_0 = f(t,\phi)$$



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Weakly nonlinear model







• Phase model
$$\frac{d\phi}{dt} - \omega_0 = f(t,\phi)$$

Weakly nonlinear model





Complex amplitude: $c = x + i \alpha y$

$$\frac{dc}{dt} + i(\omega_0 + N |c|^2)c + [\alpha(I - I_{th}) - \beta |c|^2]c = f(t,c)$$



• Phase model
$$\frac{d\phi}{dt} - \omega_0 = f(t,\phi)$$

Weakly nonlinear model

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Linear and nonlinear auto-oscillators



Auto-oscillator – autonomous dynamical system with stable limit cycle

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Weakly nonlinear model

•

$$\frac{dc}{dt} + i(\omega_0 + N|c|^2)c + [\alpha(I - I_{th}) - \beta |c|^2]c = f(t,c)$$

Nonlinear auto-oscillator: frequency depends on the amplitude

Linear and nonlinear auto-oscillators



Auto-oscillator – autonomous dynamical system with stable limit cycle

Phase model
$$\frac{d\phi}{dt} - \omega_0 = f(t,\phi)$$

Weakly nonlinear model

$$\frac{dc}{dt} + i(\omega_0 + N |c|^2)c + [\alpha(I - I_{\text{th}}) - \beta |c|^2]c = f(t, c)$$

All conventional auto-oscillators are linear.

 $|N| << \beta$

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Spin-torque oscillator





Ferromagnetic metal – strong self-interaction – strong nonlinearity

Electric current – compensation of dissipation – auto-oscillatory dynamics

Spin-torque oscillator



Electric current I

Spin-transfer torque:

$$\left(\frac{d\mathbf{M}}{dt}\right)_{\mathrm{S}} = \mathbf{T}_{\mathrm{S}} = \frac{\sigma I}{M_0} [\mathbf{M} \times [\mathbf{M} \times \mathbf{p}]]$$
$$\sigma = \frac{\varepsilon g \ \mu_{\mathrm{B}}}{2 \ e} \frac{1}{M_0 V}$$

J. Slonczewski, J. Magn. Magn. Mat. **159**, L1 (1996) L. Berger, Phys. Rev. B. **54**, 9353 (1996)



Landau-Lifshits-Gilbert-Slonczewski equation:

$$\frac{d\mathbf{M}}{dt} = \gamma [\mathbf{H}_{\rm eff} \times \mathbf{M}] + \mathbf{T}_{\rm G} + \mathbf{T}_{\rm S}$$



Oakland

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 $\gamma [\mathbf{H}_{\mathrm{eff}} imes \mathbf{M}]$ – conservative torque (precession)

Oakland

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 $\mathbf{T}_{\rm G} = -\frac{\alpha_{\rm G}\gamma}{M_0} [\mathbf{M} \times [\mathbf{M} \times \mathbf{H}_{\rm eff}]] - \begin{array}{l} \text{dissipative torque} \\ \text{(positive damping)} \end{array}$



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$$\mathbf{T}_{\rm G} = -\frac{\alpha_{\rm G}\gamma}{M_0} [\mathbf{M} \times [\mathbf{M} \times \mathbf{H}_{\rm eff}]] - \text{dissipative torque} \\ (\text{positive damping})$$
$$\mathbf{T}_{\rm S} = +\frac{\sigma I}{M_0} [\mathbf{M} \times [\mathbf{M} \times \mathbf{p}]] - \text{spin-transfer torque} \\ (\text{negative damping})$$



Landau-Lifshits-Gilbert-Slonczewski equation:

$$\frac{d\mathbf{M}}{dt} = \gamma [\mathbf{H}_{\text{eff}} \times \mathbf{M}] + \mathbf{T}_{\text{G}} + \mathbf{T}_{\text{S}}$$



When negative current-induced damping compensates natural magnetic damping, self-sustained precession of magnetization starts.





S.I. Kiselev et al., Nature 425, 380 (2003)





M.R. Pufall et al., Appl. Phys. Lett. 86, 082506 (2005)

Specific features of spin-torque oscillators





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Specific features of spin-torque oscillators





• Strong influence of thermal noise (spin-torque **NANO**-oscillator)

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Specific features of spin-torque oscillators





• Strong influence of thermal noise (spin-torque **NANO**-oscillator)

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• Strong frequency nonlinearity

M.R. Pufall *et al.*, Appl. Phys. Lett. **86**, 082506 (2005)

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$$\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = 0$$

 $p = |c|^2$ – oscillation **power** $\phi = \arg(c)$ – oscillation **phase**



Nonlinear oscillator model





 $p = |c|^2 - \text{oscillation power}$ $\phi = \arg(c) - \text{oscillation phase}$



Nonlinear oscillator model





Nonlinear oscillator model





How to find parameters of the model?



 $\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = 0$

$$\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = 0$$

- Start from the Landau-Lifshits-Gilbert-Slonczewski equation
- Rewrite it in canonical coordinates
- Perform weakly-nonlinear expansion
- Diagonalize linear part of the Hamiltonian
- Perform renormalization of non-resonant three-wave processes
- Take into account only resonant four-wave processes
- Average dissipative terms over "fast" conservative motion
- and obtain analytical results for

$$\omega(p) \qquad \qquad \Gamma_{+}(p) \qquad \qquad \Gamma_{-}(p)$$



$$\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = 0$$

$$p = |c|^{2} - \text{oscillation power}$$

$$p = |c|^{2} - \frac{1}{2} - \frac{1}{2} + \frac{1}$$

Stationary solution: $c(t) = \sqrt{p_0} \exp(-i\omega_g t + i\phi_0)$

Stationary power is determined from the condition of vanishing total damping:

$$\Gamma_{\!\scriptscriptstyle +}(p_0) = \Gamma_{\!\scriptscriptstyle -}(p_0)$$

Stationary frequency is determined by the oscillation power:

$$\omega_{\rm g} = \omega(p_0)$$



Stationary power is determined from the condition of vanishing total damping:

$$\Gamma_{\!\scriptscriptstyle +}(p_0) = \Gamma_{\!\scriptscriptstyle -}(p_0)$$

$$p_0 = rac{\zeta - 1}{\zeta + Q}$$
 $\zeta = I/I_{
m th}$ – supercriticality parameter $I_{
m th} = \Gamma_0/\sigma$ – threshold current

Stationary frequency is determined by the oscillation power:

$$\omega_{\rm g} = \omega(p_0)$$

$$\omega_{g} = \omega_{0} + Np_{0} = \omega_{0} + N\frac{\zeta - 1}{\zeta + Q}$$

 ω_0 – FMR frequency

 $N\,$ – nonlinear frequency shift
Generated frequency



Frequency as function of applied field

Frequency as function of magnetization angle



Experiment: W.H. Rippard *et al.*, Phys. Rev. Lett. **92**, 027201 (2004)

Experiment: W.H. Rippard *et al.*, Phys. Rev. B **70**, 100406 (2004)



Stochastic Langevin equation:

$$\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = \sqrt{D_{n}}f_{n}(t)$$

Random thermal noise:

$$\left\langle f_{\rm n}(t)f_{\rm n}^{*}(t')\right\rangle = 2\delta(t-t')$$

$$D_{\rm n}(p) = \Gamma_{+}(p)\eta(p) = \Gamma_{+}(p)\frac{k_{\rm B}T}{\lambda\omega(p)}$$

 η – thermal equilibrium power of oscillations: $\langle |c|^2 \rangle_{\Gamma_{-}=0} = \langle p \rangle_{\Gamma_{-}=0} = \eta$

 λ – scale factor that relates energy and power: $E(p) = \lambda \int \omega(p) dp$



Probability distribution function (PDF) $P(t, p, \phi)$ describes probability that oscillator has the power $p = |c|^2$ and the phase $\phi = \arg(c)$ at the moment of time t.

$$\frac{dP}{dt} - \frac{\partial}{\partial p} \left\{ 2p \left[\Gamma_{+}(p) - \Gamma_{-}(p) \right] P \right\} - \omega(p) \frac{\partial P}{\partial \phi} = \frac{\partial}{\partial p} \left[2p D_{n}(p) \frac{\partial P}{\partial p} \right] + \frac{D_{n}(p)}{2p} \frac{\partial^{2} P}{\partial \phi^{2}}$$

Deterministic terms describe noise-free dynamics of the oscillator Stochastic terms describe thermal diffusion in the phase space

$$D_{\rm n}(p) = \Gamma_{+}(p)\eta(p) = \Gamma_{+}(p)\frac{k_{\rm B}T}{\lambda\omega(p)}$$



Stationary probability distribution function P_0 :

- does not depend on the time t (by definition);
- does not depend on the phase ϕ (by phase-invariance of FP equation).

Ordinary differential equation for $P_0(p)$:

$$-\frac{d}{dp}\left\{2p\left[\Gamma_{+}(p)-\Gamma_{-}(p)\right]P_{0}\right\}=\frac{d}{dp}\left[2pD_{n}(p)\frac{dP_{0}}{dp}\right]$$

Stationary PDF for an arbitrary auto-oscillator:

$$P_0(p) = Z_0 \exp\left[-\frac{\lambda}{k_{\rm B}T} \int_0^p \omega(p') \left(1 - \frac{\Gamma_-(p')}{\Gamma_+(p')}\right) dp'\right]$$

Constant Z_0 is determined by the normalization condition

$$\int_{0}^{\infty} P_0(p) dp = 1$$



"Material functions" for the case of STO:

$$\Gamma_{+}(p) = \Gamma_{G}(1 + Qp) \qquad \qquad \Gamma_{-}(p) = \sigma I(1 - p) \qquad \qquad \zeta = I/I_{\text{th}} = \sigma I/\Gamma_{G}$$

Analytical expression for the stationary PDF:

$$P_{0}(p) = \frac{Q}{(1+Qp)^{\beta}} \frac{\exp[-(\zeta+Q)(1+Qp)/Q^{2}\eta]}{E_{\beta}((\zeta+Q)/Q^{2}\eta)}$$

Analytical expression for the mean oscillation power

$$\overline{p} = \frac{Q\eta}{\zeta + Q} \left[1 + \frac{\exp\left(-\left(\zeta + Q\right)/Q^2\eta\right)}{E_{\beta}\left((\zeta + Q)/Q^2\eta\right)} \right] + \frac{\zeta - 1}{\zeta + Q}$$

Here $\beta = (1+Q)\zeta/Q^2\eta$

$$E_{\beta}(x) = \int_{1}^{\infty} e^{-xt} t^{-\beta} dt$$
 – exponential integral function





Experiment: Q. Mistral et al., Appl. Phys. Lett. 88, 192507 (2006).

Theory: V. Tiberkevich *et al.*, Appl. Phys. Lett. **91**, 192506 (2007).

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Linewidth of a conventional oscillator



Classical result (see, e.g., A. Blaquiere, *Nonlinear System Analysis* (Acad. Press, N.Y., 1966)): Full linewidth of an electrical oscillator

$$2\Delta\omega = \frac{k_{\rm B}T R_0 \omega_0^2}{U_0^2}$$





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$$2\Delta\omega = \frac{k_{\rm B}T R_0 \omega_0^2}{U_0^2}$$

Physical interpretation of the classical result

$$2\Delta\omega = \Gamma_0 \frac{k_{\rm B}T}{E_0}$$





Frequency

Equilibrium half-linewidth





Oscillation energy

Linewidth of a laser



Quantum limit for the linewidth of a single-mode laser (Schawlow-Townes limit) [A.L. Schawlow and C.H. Townes, Phys. Rev. **112**, 1940 (1958)]

$$2\Delta\omega = \frac{\hbar\omega_0\Gamma_0^2}{2P_{\rm out}}$$

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$$2\Delta\omega = \frac{\hbar\omega_0\Gamma_0^2}{2P_{\rm out}}$$

Physical interpretation of the classical result

$$2\Delta\omega = \Gamma_0 \frac{k_{\rm B}T}{E_0}$$

$$k_{\rm B}T = \frac{\hbar\omega_0}{2}$$

Effective thermal energy

$$E_0 = P_{\rm out} / \Gamma_0$$

Oscillation energy



Experiment by W.H. Rippard *et al.*, Theoretical result [J.-V. Kim, PRB **73**, 174412 (2006)]: *DARPA Review* (2004).



$$2\Delta\omega \approx \alpha_{\rm G} \frac{\partial \omega_0}{\partial H} \frac{k_{\rm B}T}{M_0 V_{\rm eff} p_0}$$



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Physical interpretation:

$$2\Delta\omega = \Gamma_0 \frac{k_{\rm B}T}{E_0}$$

$$2\Delta f_{\rm exp} = 2\Delta \omega / 2\pi = 13.5 \,\mathrm{MHz}$$

 $2\Delta f_{\text{theor}} = 2\Delta \omega / 2\pi = 0.35 \text{ MHz}$



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$$2\Delta f_{exp} = 2\Delta \omega / 2\pi = 13.5 \text{ MHz}$$
 $2\Delta f_{theor} = 2\Delta \omega / 2\pi = 0.35 \text{ MHz}$

This theory does assumes that the frequency is constant

 $\omega(p) = \omega_0 = \text{const}$



Power spectrum $S(\Omega)$ is the Fourier transform of the autocorrelation function $K(\tau)$:

 $S(\Omega) = \int K(\tau) e^{i\Omega\tau} d\tau \qquad \qquad K(\tau) = \left\langle c(t+\tau)c^*(t) \right\rangle$ two-time function

Autocorrelation function $K(\tau)$ can not be found from the stationary PDF. Ways to proceed:

- Solve non-stationary Fokker-Planck equation [J.-V. Kim *et al.*, Phys. Rev. Lett. **100**, 167201 (2008)];
- Analyze stochastic Langevin equation.

$$\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = \sqrt{D_{n}}f_{n}(t)$$

Power and phase fluctuations





Power fluctuations are weak

$$\frac{\Delta p}{p_0} \approx \sqrt{\frac{k_{\rm B}T}{E(p_0)}} << 1$$

Oscillations – phase-modulated process:

$$c(t) = \sqrt{p(t)}e^{i\phi(t)} \approx \sqrt{p_0}e^{i\phi(t)}$$

Autocorrelation function:

 $K(\tau) \approx p_0 \left\langle \exp[i\phi(\tau) - i\phi(0)] \right\rangle$

Linewidth of any oscillator is determined by the phase fluctuations

Linearized power-phase equations



Stochastic Langevin equation: $\frac{dc}{dt} + i\omega(p)c + \Gamma_{+}(p)c - \Gamma_{-}(p)c = \sqrt{D_n}f_n(t)$

Linearized power-phase equations



Stochastic Langevin equation:
$$\frac{dc}{dt} + i\omega(p)c + \Gamma_+(p)c - \Gamma_-(p)c = \sqrt{D_n}f_n(t)$$

Power-phase ansatz:
$$c(t) = \sqrt{p_0 + \delta p(t)} e^{i\phi(t)}$$
 $|\delta p| \ll p_0$



 $|\delta p| << p_0$

Stochastic Langevin equation:
$$\frac{dc}{dt} + i\omega(p)c + \Gamma_+(p)c - \Gamma_-(p)c = \sqrt{D_n}f_n(t)$$

 $c(t) = \sqrt{p_0 + \delta p(t)} e^{i\phi(t)}$

Stochastic power-phase equations:

Power-phase ansatz:

$$\frac{d\delta p}{dt} + 2\Gamma_{\text{eff}} \ \delta p = 2\sqrt{D_{\text{n}}p_0} \operatorname{Re}[f_{\text{n}}(t)e^{-i\phi}]$$
$$\frac{d\phi}{dt} + \omega(p_0) = \sqrt{\frac{D_{\text{n}}}{p_0}} \operatorname{Im}[f_{\text{n}}(t)e^{-i\phi}] + N \ \delta p$$

Linear system of equations. Can be solved in general case.

Effective damping: $\Gamma_{\rm eff} = (G_+ - G_-)p_0$ $G_{\pm} = d\Gamma_{\pm}(p)/dp$

Nonlinear frequency shift coefficient: $N = d\omega(p)/dp$

Nonlinear frequency shift creates additional source of the phase noise



Correlation function for power fluctuations:

$$\langle \delta p(t+\tau) \delta p(t) \rangle = p_0^2 \left(\frac{\Gamma_+}{\Gamma_{\rm eff}} \right) \frac{k_{\rm B} T}{E(p_0)} e^{-2\Gamma_{\rm eff}|\tau|}$$



Correlation function for power fluctuations:

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uations are small

Power fluctuations are small ~



Correlation function for power fluctuations:

$$\left< \delta p(t+\tau) \delta p(t) \right> = p_0^2 \left(\frac{\Gamma_+}{\Gamma_{\text{eff}}} \right) \frac{k_{\text{B}} T}{E(p_0)} e^{-2\Gamma_{\text{eff}}|\tau|}$$

Power fluc

Non-zero correlation time of power fluctuations

Additional noise source $-N \delta p$ for the phase fluctuations is Gaussian, but not "white"



$$\left\langle \phi(t+\tau) - \phi(t) \right\rangle = -\omega(p_0)\tau$$



$$\langle \phi(t+\tau) - \phi(t) \rangle = -\omega(p_0)\tau$$

Determines mean oscillation frequency



$$\langle \phi(t+\tau) - \phi(t) \rangle = -\omega(p_0)\tau$$

Determines mean oscillation frequency

Variance of the phase difference:

$$\Delta \phi^2(\tau) = \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} \left[|\tau| + \nu^2 \left(|\tau| - \frac{1 - e^{-2\Gamma_{\rm eff}|\tau|}}{2\Gamma_{\rm eff}} \right) \right]$$

$$v = \frac{Np_0}{\Gamma_{\text{eff}}} = \frac{N}{G_+ - G_-} - \text{dimensionless nonlinear frequency shift}$$



$$\langle \phi(t+\tau) - \phi(t) \rangle = -\omega(p_0)\tau$$

Determines mean oscillation frequency

Variance of the phase difference:

$$\Delta \phi^{2}(\tau) = \Gamma_{+} \frac{k_{\rm B} T}{E(p_{0})} \left[|\tau| + \nu^{2} \left(|\tau| - \frac{1 - e^{-2\Gamma_{\rm eff}|\tau|}}{2\Gamma_{\rm eff}} \right) \right] \qquad \text{Determines oscillation}$$
linewidth

$$\nu = \frac{Np_0}{\Gamma_{\text{eff}}} = \frac{N}{G_+ - G_-} - \text{dimensionless nonlinear frequency shift}$$

Auto-correlation function:

$$K(\tau) = p_0 e^{-i\omega(p_0)\tau} \exp\left[-\frac{1}{2}\Delta\phi^2(\tau)\right]$$

Low-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} (1 + \nu^2) |\tau|$$

"Random walk" of the phase

Low-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} (1 + \nu^2) |\tau|$$

"Random walk" of the phase

Lorentzian lineshape with the full linewidth

$$2\Delta\omega = (1+\nu^2)\Gamma_+ \frac{k_{\rm B}T}{E(p_0)} = (1+\nu^2) 2\Delta\omega_{\rm lin}$$

Frequency nonlinearity broadens linewidth by the factor

$$1 + v^2 = 1 + \left(\frac{N}{G_+ - G_-}\right)^2$$

Low-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} (1 + \nu^2) |\tau|$$

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Frequency nonlinearity broadens linewidth by the factor

$$1 + v^2 = 1 + \left(\frac{N}{G_+ - G_-}\right)^2$$

Region of validity
$$k_{\rm B}T \ll \left(\frac{\Gamma_{\rm eff}}{\Gamma_{\rm +}}\right) \frac{E(p_0)}{1+\nu^2} \sim 300 \, {\rm K}$$

High-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} \nu^2 \Gamma_{\rm eff} \ \tau^2$$

"Inhomogeneous broadening" of the frequencies

High-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} \nu^2 \Gamma_{\rm eff} \ \tau^2$$

"Inhomogeneous broadening" of the frequencies

Gaussian lineshape with the full linewidth

$$2\Delta\omega_* = 2 |\nu| \sqrt{\Gamma_+ \Gamma_{\rm eff}} \sqrt{\frac{k_{\rm B}T}{E(p_0)}}$$

Different dependence of the linewidth on the temperature:

$$2\Delta\omega_* \sim \sqrt{T}$$

High-temperature asymptote



$$\Delta \phi^2(\tau) \approx \Gamma_+ \frac{k_{\rm B}T}{E(p_0)} \nu^2 \Gamma_{\rm eff} \ \tau^2$$

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Different dependence of the linewidth on the temperature:

$$2\Delta\omega_* \sim \sqrt{T}$$

Region of validity
$$k_{\rm B}T >> \left(\frac{\Gamma_{\rm eff}}{\Gamma_{\rm +}}\right) \frac{E(p_0)}{v^2} \sim 300 \text{ K}$$

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Temperature dependence of STO linewidth



Experiment: J. Sankey et al., Phys. Rev. B 72, 224427 (2005)



Low-temperature asymptote gives correct order-of-magnitude estimation of the linewidth.



$$2\Delta\omega = (1+\nu^{2})\Gamma_{+}\frac{k_{\rm B}T}{E(p_{0})} = \left(1 + \left(\frac{N}{G_{+}-G_{-}}\right)^{2}\right)\Gamma_{+}\frac{k_{\rm B}T}{E(p_{0})}$$

Nonlinear frequency shift coefficient N strongly depends on the orientation of the bias magnetic field




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Nonlinear frequency shift coefficient N strongly depends on the orientation of the bias magnetic field





Out-of-plane magnetization



Experiment: W.H. Rippard et al., Phys. Rev. B 74, 224409 (2006)

Theory: J.-V. Kim, V. Tiberkevich and A. Slavin, Phys. Rev. Lett. 100, 017207 (2008)



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Nonlinear frequency shift coefficient N strongly depends on the orientation of the bias magnetic field



Angular dependence of the linewidth



In-plane magnetization



Experiment: K. V. Thadani *et al.*, arXiv: 0803.2871 (2008)

Outline



Introduction

- Linear and nonlinear auto-oscillators
- Spin-torque oscillator (STO)
- Stochastic model of a nonlinear auto-oscillator
- Generation linewidth of a nonlinear auto-oscillator
 - Theoretical results
 - Comparison with experiment (STO)
- Summary



• "Nonlinear" auto-oscillators (oscillators with power-dependent frequency) are simple dynamical systems that can be described by universal model, but which have not been studied previously

• There are a number of qualitative differences in the dynamics of "linear" and "nonlinear" oscillators:

- Different temperature regimes of generation linewidth (low- and high-temperature asymptotes)
- Different mechanism of phase-locking of "nonlinear" oscillators [A. Slavin and V. Tiberkevich, Phys. Rev. B 72, 092407 (2005); *ibid.*, 74, 104401 (2006)]
- Possibility of chaotic regime of mutual phase-locking [preliminary results]

• Spin-torque oscillator (STO) is the first experimental realization of a "nonlinear" oscillator. Analytical nonlinear oscillator model correctly describes both deterministic and stochastic properties of STOs.