

# Madelung Fluid Description of gNLS Eq. Special Solutions and their Stability

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- Madelung Hydrodynamic Description
  - Madelung's Approach - Generalized NLS Equations
  - Generalized NLS Equation

$$i\frac{\partial\Psi}{\partial t} + \frac{1}{2}\frac{\partial^2\Psi}{\partial x^2} + 2i\Psi^2\frac{\partial\Psi^*}{\partial x} + \alpha U(|\Psi|^2)\Psi = 0$$

- Bright Soliton Solution
- Periodic Solutions
- Solution Stability

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# Madelung Hydrodynamic Description

Hydrodynamic description of quantum mechanics

E. Madelung - 1926

$$i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + mU(x)\Psi$$

$$\Psi = \sqrt{\rho} e^{i\theta}$$

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho v) = 0$$

$$\left( \frac{\partial}{\partial t} + v \frac{\partial}{\partial x} \right) v = \frac{\hbar^2}{2m} \frac{\partial}{\partial x} \left( \frac{1}{\sqrt{\rho}} \frac{\partial^2 \sqrt{\rho}}{\partial x^2} \right) - \frac{\partial U}{\partial x}$$



$$\rho = |\Psi|^2$$

fluid density

$$v = \frac{\hbar}{m} \frac{\partial \theta}{\partial x}$$

fluid velocity

$$\frac{\hbar^2}{2m} \frac{\partial}{\partial x} \left( \frac{1}{\sqrt{\rho}} \frac{\partial^2 \sqrt{\rho}}{\partial x^2} \right)$$

quantum Bohm's potential

$$j = \frac{\hbar}{2m} \left( \Psi^* \frac{\partial \Psi}{\partial x} - \Psi \frac{\partial \Psi^*}{\partial x} \right) = \rho v$$

# Madelung's Approach - Generalized NLS Equations

Series of papers R. Fedele, H. Schamel, P.K. Shukla, V.I. Karpman (2002) used MA to discuss generalized NLS eq.

$$i\alpha \frac{\partial \Psi}{\partial t} + \frac{\alpha^2}{2} \frac{\partial^2 \Psi}{\partial x^2} - U(|\Psi|^2)\Psi = 0$$

For  $U(|\Psi|^2) = |\Psi|^2$  is the well known completely integrable cubic NLS eq.

$$U(|\Psi|^2) = q_1 |\Psi|^{2\beta} + q_2 |\Psi|^{4\beta}$$

( $\beta = 1$ , cubic + quintic nonlinearity)

Recently we used MA to discuss generalized derivative NLS eqs. (D. Grecu, A.T. Grecu, A. Visinescu, R. Fedele, S. DeNicola - 2008)

$$i\alpha \frac{\partial \Psi}{\partial t} + \frac{\alpha^2}{2} \frac{\partial^2 \Psi}{\partial x^2} + i\gamma \frac{\partial}{\partial x} \left( U(|\Psi|^2) \Psi \right) = 0 \quad \text{gdNLS - 1}$$

$$i\alpha \frac{\partial \Psi}{\partial t} + \frac{\alpha^2}{2} \frac{\partial^2 \Psi}{\partial x^2} + i\gamma U(|\Psi|^2) \frac{\partial \Psi}{\partial x} = 0 \quad \text{gdNLS - 2}$$

For  $U(|\Psi|^2) = |\Psi|^2$  they transform into completely integrable equations.

- ① R. Fedele, H. Schamel, *Eur. Phys. J B* **27**, 313 (2002)
- ② R. Fedele, *Physica Scripta* **65**, 502 (2002)
- ③ R. Fedele, H. Schamel, P.K. Shukla, *Physica Scripta T* **98**, 18 (2002)
- ④ R. Fedele, H. Schamel, V.I. Karpman, P.K. Shukla, *J. Phys. A: Math. Gen* **36**, 1169 (2003)
- ⑤ D. Grecu, A.T. Grecu, A. Visinescu, R. Fedele, S.DeNicola, *J. Nonlinear Math. Phys* - to be published (Proc. NEEDS-2007)
- ⑥ A. Visinescu, S. DeNicola, R. Fedele, D. Grecu, *Proc.Int. Conf. FARPhys 2007, lassy* - to be published

We are studying now mixed eqs. like

$$i\frac{\partial\Psi}{\partial t} + \frac{1}{2}\frac{\partial^2\Psi}{\partial x^2} + 2i\Psi^2\frac{\partial\Psi^*}{\partial x} + \alpha U(|\Psi|^2)\Psi = 0$$

For  $U(|\Psi|^2) = |\Psi|^4 = |\Psi|^{2\beta}$  it is completely integrable (Ablowitz et al - 1980, Gerdjikov and Ivanov - 1983, Tsuschida - 2002)

$$\Psi = \sqrt{\rho}e^{i\theta}$$

$$\rho(x, t) = |\Psi|^2, \quad v(x, t) = \frac{\partial\theta(x, t)}{\partial x}$$

Separating the real and imaginary part we get

- equation of continuity

$$\frac{\partial \rho}{\partial t} = \frac{\partial}{\partial x} (\rho v + \rho^2)$$

and

- equation of motion for fluid velocity

$$\left( -\frac{\partial}{\partial t} + v \frac{\partial}{\partial x} \right) v = \frac{1}{2} \frac{\partial}{\partial x} \left( \frac{1}{\sqrt{\rho}} \frac{\partial^2 \sqrt{\rho}}{\partial x^2} \right) + 2 \frac{\partial(v\rho)}{\partial x} + \alpha \frac{\partial U}{\partial \rho} \frac{\partial \rho}{\partial x}$$

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Using a series of transformations (Fedele et al. 2002), the equation of motion can be written

$$\rho \frac{\partial v}{\partial t} - v \frac{\partial \rho}{\partial t} + 2 \left[ c_0(t) + \int \frac{\partial v}{\partial t} dx \right] \frac{\partial \rho}{\partial x} + \frac{1}{4} \frac{\partial^3 \rho}{\partial x^3} + \alpha \left( \rho \frac{dU}{d\rho} + 2U \right) \frac{\partial \rho}{\partial x} + 2\rho^2 \frac{\partial v}{\partial x} + 4v \frac{\partial(\rho^2)}{\partial x} = 0$$

a KdV-type equation



# NO Solutions with Constant Current Velocity

Indeed if  $v = v_0$  from the equation of continuity we get

$$\rho_t - (v_0 + 2\rho)\rho_x = 0$$

If

$$f(x) = \rho(x, t = 0)$$

is the initial solution, then

$$\rho(x, t) = f[x + (v_0 + 2\rho)t]$$

which is incompatible with the dispersive equation of motion

# Motion with Stationary Profile Current Velocity

$$\rho(x, t) = \rho(\xi) \quad v(x, t) = v(\xi)$$
$$\xi = x + u_0 t$$

Eq. of continuity becomes

$$\frac{d}{d\xi} (-u_0 \rho + v \rho + \rho^2) = 0$$

$$v = u_0 - \rho + \frac{A_0}{\rho}$$

If  $\rho \rightarrow 0$  for  $|\xi| \rightarrow \infty$  then  $A_0 \equiv 0$   
(bright soliton case)

$$v = u_0 - \rho$$

the KdV-type equation becomes an ordinary differential equation

$$\frac{1}{4} \frac{d^3 \rho}{d\xi^3} + \alpha \left( \rho \frac{dU}{d\rho} + 2U \right) \frac{d\rho}{d\xi} + 2 \left( c_0 + \frac{u_0^2}{2} \right) \frac{d\rho}{d\xi} + 3u_0 \frac{d(\rho^2)}{d\xi} - \frac{10}{3} \frac{d(\rho^3)}{d\xi} = 0$$

# Solution for $\beta = 2, \alpha = 1$

$$\rho = \frac{b^2}{\sqrt{b^2 - u_0^2} \sinh 2b(\xi - \xi_0) + u_0}$$

and the phase is given by  $\theta = \int (u_0 - \rho) d\xi$

$$\theta = \theta_0 + u_0 \xi - 3 \tanh^{-1} \frac{u_0 \tanh \frac{\xi}{2} - \sqrt{b^2 - u_0^2}}{b}$$

where

$$b^2 = -(2c_0 + u_0^2) > 0$$

It is easily seen that we can find solutions for  $\beta = 1, 2, 3$  and different values for  $\alpha$ . The case  $\beta = 2$  and  $\alpha = 4$  corresponds to the integrable equation.

# Periodic Solution for $\alpha = 4$ and $\beta = 2$

From the KdV-type equation

$$\begin{aligned} & \rho \frac{\partial v}{\partial t} - v \frac{\partial \rho}{\partial t} + 2 \left[ c_0(t) + \int \frac{\partial v}{\partial t} dx \right] \frac{\partial \rho}{\partial x} + \\ & + \frac{1}{4} \frac{\partial^3 \rho}{\partial x^3} + \alpha \left( \rho \frac{dU}{d\rho} + 2U \right) \frac{\partial \rho}{\partial x} + 2\rho^2 \frac{\partial v}{\partial x} + 4v \frac{\partial(\rho^2)}{\partial x} = 0 \end{aligned}$$

by substituting

$$\xi = x + u_0 t, \quad v = u_0 - \rho + \frac{A}{\rho}$$

after two integration we get

$$\frac{1}{4} \left( \frac{d\rho}{dx} \right)^2 = -[\rho^4 + 2u_0\rho^3 + (c_0 + \frac{u_0^2}{2} + 5A_0)\rho^2 + B\rho + C] = -P_4(\rho)$$

We consider the case with 4 real roots of  $P_4$ ,  $(\rho_1, \rho_2, \rho_3, \rho_4)$ , at least 2 positive,  $0 \leq \rho_2 < \rho < \rho_1$ . The periodic solution of gNLS can be expressed in terms of Jacobi elliptic functions, as

$$\rho = \rho_3 + \frac{\rho_2 - \rho_3}{1 - \lambda^2 \operatorname{sn}^2 u}$$

where

$$k^2 = \frac{(\rho_1 - \rho_2)(\rho_3 - \rho_4)}{(\rho_1 - \rho_3)(\rho_2 - \rho_4)}, \quad k^2 < \lambda^2 = \frac{\rho_1 - \rho_2}{\rho_1 - \rho_3} < 1$$
$$u = \frac{2}{g} \xi, \quad g = \frac{2}{\sqrt{(\rho_1 - \rho_3)(\rho_2 - \rho_4)}}$$

# Stability - Vakhitov- Kolokolov Criterion

$$i\frac{\partial\Psi}{\partial t} + \frac{\partial^2\Psi}{\partial x^2} + f(|\Psi|)\Psi = 0$$

ground state (stationary state)

$$\Psi = e^{i\omega t}\Phi(x, \omega)$$
$$N(\omega) = \int \Phi^2(x, \omega) dx$$

Vakhitov- Kolokolov criterion: instability if

$$\frac{dN(\omega)}{d\omega} < 0$$

M.G. Vakhitov, A.A. Kolokolov, *Izv. Vyssh. Uch. Izv. Radiofizica*  
**16**, 1020 (1973)

M.I. Weinstein, *Comm. Pure Appl. Math* **39**, 51 (1986)

D.E. Pelinovski, V.V. Afanasyev, Yu.S. Kivshar *Phys.Rev.E* **53**,  
1940 (1996) Going beyond linear analysis

$$\Psi(x, t) = \phi(x, t) e^{i \int_0^t \omega(t') dt'}$$

$$\phi(x, t) = \Phi(x, \omega(t)) + \phi_1(x, t) + \phi_2(x, t) + \dots$$

instability-induced evolution is

- slow in time
- almost adiabatic

result: an equation (second order differential nonlinear equation) for  $\omega(t)$ ; various instability scenarios

D.E. Pelinovski, V.V. Afanasyev, Yu.S. Kivshar *Phys.Rev.E* **54**,  
2015 (1996) - dark soliton stability



# Vakhitov-Kolokolov Criterion for gNLS eq.

Apply Vakhitov-Kolokolov criterion for

$$iq_t = \frac{1}{2}q_{xx} + 2iq^2q_x^* + 2q_0|q|^2q$$

Stationary solution

$$q(x, t) = e^{-i\frac{\omega}{2}t} e^{i\theta(x, \omega)} \Phi(x, \omega)$$

Separating imaginary and real part, we obtain from the imaginary one

$$\frac{d\theta}{dx} = -\Phi^2$$

and from the real part

$$\left(\frac{d\Phi}{dx}\right)^2 = \omega\Phi^2 - 2q_0\Phi^4 + \frac{5}{3}\Phi^6$$

$$\phi = \frac{\sqrt{\omega}}{\left(\frac{\sqrt{\Delta}}{2} \sinh 2\sqrt{\omega}x + q_0\right)^{\frac{1}{2}}}$$

where

$$\Delta = \frac{5\omega}{3} - q_0^2 > 0$$

$$N(\omega) = \int_{-\infty}^{\infty} \phi^2 dx = \sqrt{\frac{\omega}{\gamma}} \int_{-\infty}^{\infty} \frac{dx}{\sinh x + \gamma}$$
$$\gamma = \frac{2q_0}{\sqrt{\Delta}}$$

$\gamma > 1$  means  $\frac{3q_0^2}{5} < \omega < 3q_0^2$

$$N(\omega) = \sqrt{\frac{3\omega}{5\omega - 3q_0^2}} \frac{1}{\sqrt{\gamma^2 - 1}} \ln \frac{\gamma + \sqrt{\gamma^2 - 1}}{\gamma - \sqrt{\gamma^2 - 1}}$$

$$\frac{dN}{d\omega} < 0 \quad \text{unstable}$$

$\gamma < 1$  means  $\omega > 3q_0^2$

$$N(\omega) = \sqrt{\frac{3\omega}{5\omega - 3q_0^2}} \frac{2}{\sqrt{\gamma^2 - 1}} \operatorname{artg} \frac{\gamma}{\sqrt{1 - \gamma^2}}$$

$$\frac{dN}{d\omega} > 0 \quad \text{stable}$$

Difficult to extend to other nonlinearities. We are trying to study the stability (using the VK criterion) for a simpler mixed dNLS+NLS equation

$$iq_t + q_{xx} + ia_1|q|^{2\beta_1}q_x + a_2|q|^{2\beta_2}q = 0$$