

Stability and instability dynamics of lattice solitons

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UC Merced

- 10th campus of University of California opened 2005
- 2008–9: 2500 students, @ full build-out: 25,000
- Applied Mathematical Sciences major + graduate



Outline

1. Soliton stability in homogeneous NLS
2. Stability theory for lattice solitons
3. Instability dynamics: asymptotics & computations
4. Conclusions

Collaborators:

- Yonatan Sivan, Tel Aviv University, Israel
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Experiments with lattice solitons

- optical media with modulated refractive index – Segev; Christodoulides; Kivshar; Chen; ... – application to optical computing, Photonic Crystal fibers, ...
- Bose-Einstein condensates with optically induced lattices – Cornell; ...
- solitons are localized NL dispersive waves that propagate in lattice-type potentials while maintaining their shape
- observed solitons are usually stable

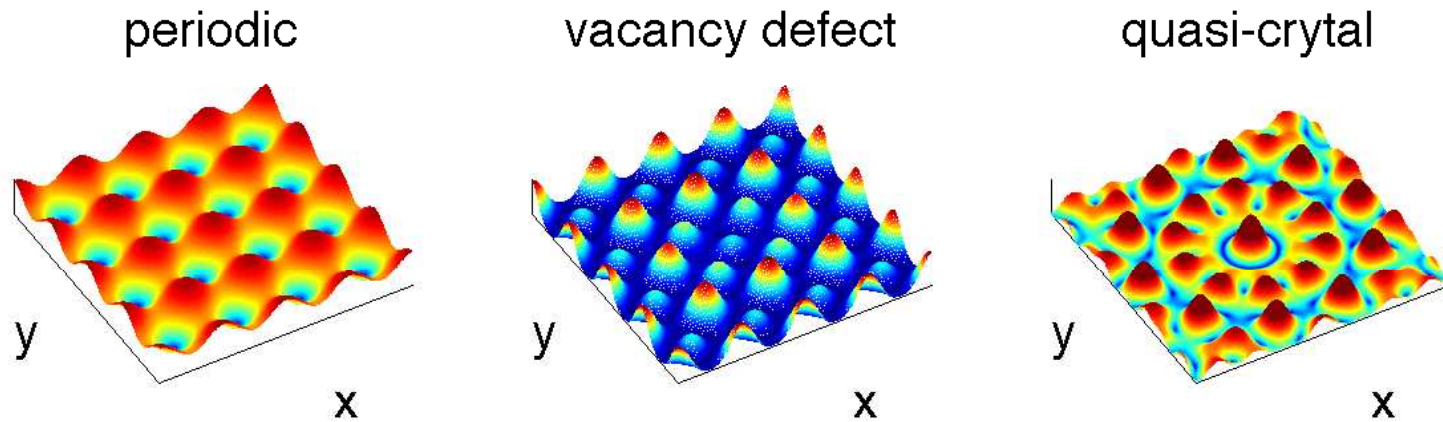
Inhomogeneous NLS model

NL Maxwell + refractive index modulation \implies focusing
inhomogeneous nonlinear Schrödinger (NLS) model

$$i\psi_t(\mathbf{x}, t) + \Delta\psi + |\psi|^{2\sigma}\psi - V(\mathbf{x})\psi = 0, \quad \psi(\mathbf{x}, 0) = \psi_0(\mathbf{x}),$$

- ψ = dimensionless complex electric field
- t = time or propagation direction
- $\mathbf{x} \in \mathbb{R}^d$, $\Delta \equiv \sum_{i=1}^d \partial_{x_i x_i}^2$ (diffraction/dispersion)
- $\sigma = 1$: Kerr effect (cubic NLS)
- $V(\mathbf{x})$ = modulation of linear refractive index
- also saturable NL, NL potentials, ...

Examples of potentials



- can be extended, a-symmetric, a-periodic, ...
- solitons can be computed
- theory can be challenging

Rigorous theory

Existence of solitons ($V \equiv 0$)

$$i\psi_t(\mathbf{x}, t) + \Delta\psi + |\psi|^{2\sigma}\psi = 0$$

Ansatz: $\psi(\mathbf{x}, t) = f_E(\mathbf{x})e^{iEt}$

- E = propagation constant
- $f_E(\mathbf{x})$ = real profile, positive bright soliton satisfies bound-state eqn

$$\hookrightarrow [-\Delta - (f_E)^{2\sigma}] f_E = -E f_E, \quad f_E(|\mathbf{x}|) \xrightarrow{|\mathbf{x}| \rightarrow \infty} 0$$

- ground states: $\exists f_E(\mathbf{x}) = R_{\sigma,d}(|\mathbf{x}|; E) > 0$, e.g.:
 - $\sigma = 1, d = 1$: integrable (1+1)D NLS, $\text{sech}(x)$
 - $\sigma = 1, d = 2$: non-integrable (2+1)D NLS, $R(r)$

Orbital stability ($V \equiv 0$)

$$i\psi_t(\mathbf{x}, t) + \Delta\psi + |\psi|^{2\sigma}\psi = 0$$

- Fundamental scale invariants:
 - phase: $\psi \rightarrow \psi e^{i\gamma}$
 - translation: $\psi \rightarrow \psi(\mathbf{x} + \mathbf{x}_0)$
- f_E is “orbitally stable” if $\psi(\mathbf{x}, t)$ remains close to $\psi_0 = f_E + \varepsilon$ for all time modulo phase & translation

$$\rho_E^2[\psi, f_E](t) \equiv \inf_{\mathbf{x}_0 \in \mathbb{R}^d} \inf_{\gamma \in [0, 2\pi)} \left[\|\nabla\psi(\mathbf{x} + \mathbf{x}_0, t)e^{i\gamma} - \nabla f_E(\mathbf{x})\|_2^2 + E\|\psi(\mathbf{x} + \mathbf{x}_0, t)e^{i\gamma} - f_E(\mathbf{x})\|_2^2 \right]$$

- orbital (Lyapunov) stability \gg linear stability

Stability theory ($V \equiv 0$)

A ground state f_E of the homogeneous NLS is orbitally stable iff it satisfies *power-slope/V-K* condition

$$\frac{dP(E)}{dE} > 0, \quad P(E) \equiv \|f_E\|_2^2 = \int f_E^2 d\mathbf{x}$$

- Vakhitov & Kolokolov (1973); Weinstein (1985, 1986); Grillakis, Shatah, & Strauss (1987)
- soliton is stable $\iff \sigma d < 2$
- instability manifested in amplitude, e.g., collapse
- many studies use this criterion

Inhomogeneous NLS

$$i\psi_t(\mathbf{x}, t) + \Delta\psi + |\psi|^{2\sigma}\psi - V(\mathbf{x})\psi = 0$$

$$\hookrightarrow [-\Delta + V(\mathbf{x}) - (f_E)^{2\sigma}] f_E = -E f_E$$

- no translation invariance
- orbital stability redefined: ψ remains close to f_E modulo phase (alone)
- most studies rely on power-slope (V-K) condition
- rigorous studies: need “*spectral condition*” as well, e.g., Rose & Weinstein (1988); Oh (1989); Fukuizumi & Ohta (2002); Stuart (2006); Fibich, Sivan, & Weinstein (2006); Rapti *et al.* (2007); Sivan *et al.* (2008)
- no general proof

Stability theorem

Ilan & Weinstein (preprint): *A positive bright soliton, f_E , is orbitally stable if it satisfies two conditions*

1. *power-slope/V-K*: $\frac{dP}{dE} > 0$

2. *spectral condition*:

$$L_+ = -\Delta + E + V(\mathbf{x}) - (2\sigma + 1)(f_E)^{2\sigma}$$

has at most one (simple) negative e-v

- $V(\mathbf{x}) \in \mathbb{R}$, periodic, defect, quasi-crystal, ...
- f_E can be centered @ any critical point of $V(\mathbf{x})$
- can check both condition numerically

Linearized operators

Linearize NLS eqn around f_E . Get

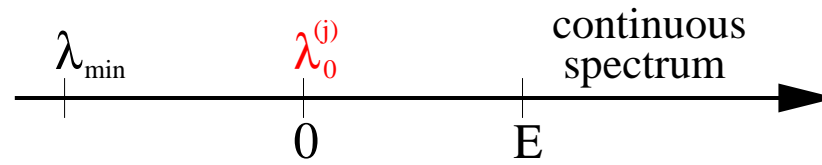
$$L_- \equiv -\Delta + E + V(\mathbf{x}) - (f_E)^{2\sigma}$$

$$L_+ \equiv -\Delta + E + V(\mathbf{x}) - (2\sigma + 1)(f_E)^{2\sigma}$$

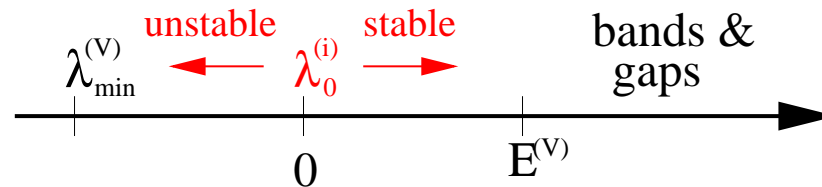
- orbital stability requires bounding L_{\pm}
- $L_- f_E = 0$; 0 is the smallest e-v & is simple
- for L_+ :
 - $\lambda_{\min} < 0$
 - no translation invariance $\implies \lambda_0^{(i)}$ shifted from 0

Spectrum of L_+

$$V(\mathbf{x}) \equiv 0 \implies \lambda_0^{(i)} = 0 \quad (i = 1 \dots d)$$



$$V(\mathbf{x}) \neq 0 \implies \lambda_0^{(i)} \neq 0 \quad (i = 1 \dots d)$$



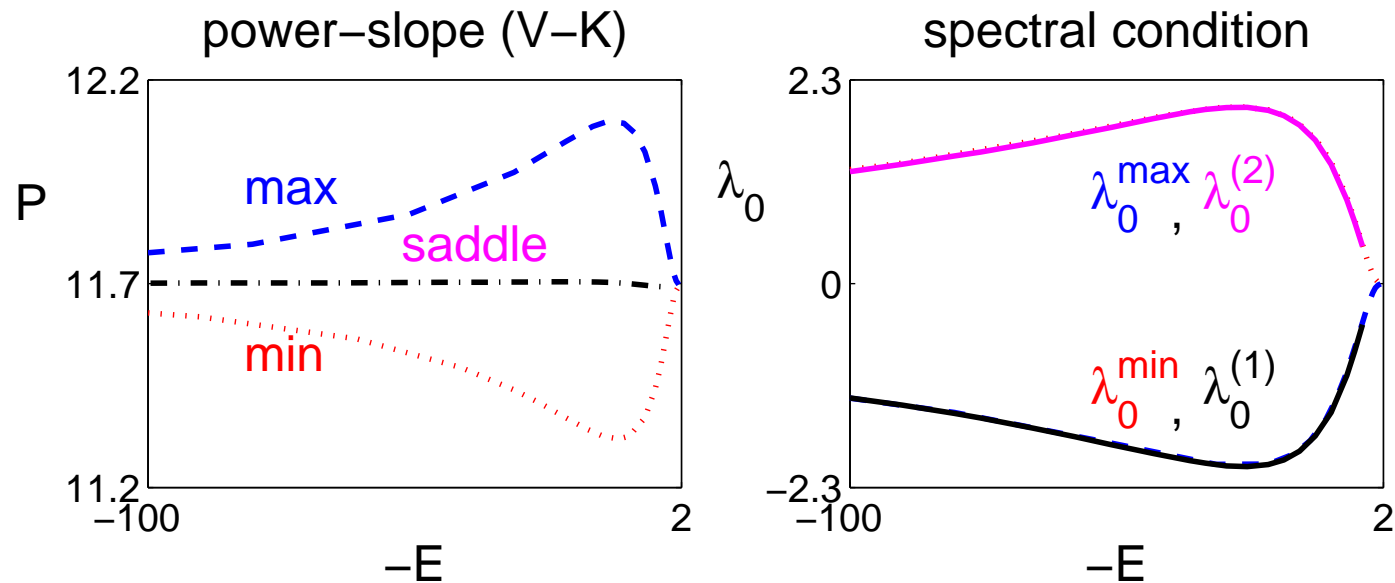
Conclusion: unstable if $\exists \lambda_0^{(i)} < 0$

Sketch of proof

- Lyapunov functional $\mathcal{E}[\psi] = H[\psi] - EP[\psi]$,
 $H \equiv$ Hamiltonian
- bound $\delta^2 \mathcal{E}[\psi] \implies$ bound L_{\pm}
- upper bounds using Gagliardo-Nirenberg inequalities
- lower bound of L_- : 0 is simple e-v of L_- ala Perron-Frobenius (cf. Reed & Simon IV)
- lower bound of L_+ : use Lagrange multipliers. Need both power-slope & **spectral condition**

Stability conditions

$$V(x, y) = 2.5 [\cos^2(2\pi x) + \cos^2(2\pi y)]$$



- power-slope (V-K) & spectral conditions are independent
- orbital stability requires both conditions

Interim summary

Rigorous theory: soliton is orbitally stable iff

1. **power-slope/V-K:** $\frac{dP}{dE} > 0$
2. **spectral condition:** $\forall i, \lambda_0^{(i)} > 0$

Questions:

1. What happens if only one condition is satisfied?
2. Qualitative/quantitative measure of instabilities?

Need asymptotic + computational tools!

Instability dynamics

Asymptotics

Sivan, Ilan, & Fibich (2008, preprint):

- $\left| \frac{dP}{d\mu} \right|$ determines strength of **amplitude** (in)stability
- $|\lambda_0^{(i)}|$ determine strength of **drift** (in)stability
 - short-time dynamics of center of mass:

$$\frac{d^2 \langle x_i \rangle}{dt^2} \sim -C^2 \lambda_0^{(i)} \langle x_i \rangle ,$$

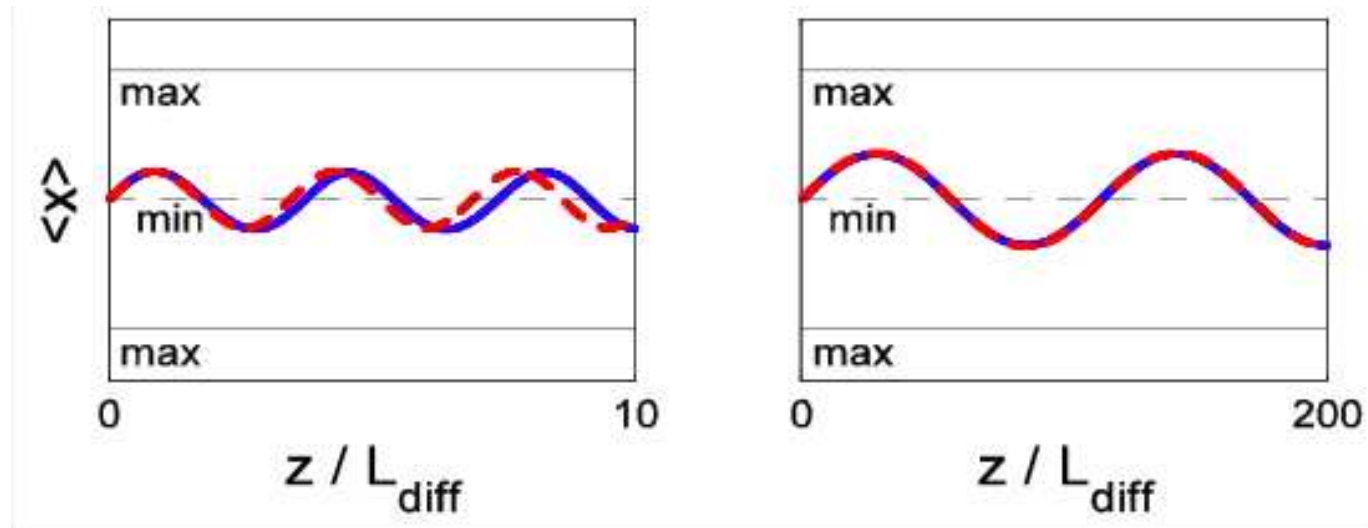
$$C^2 \equiv \frac{\langle f_E, f_E \rangle}{\langle f_E, (L_-)^{-1} f_E \rangle} > 0$$

- usually drift-stable when @ minimum of $V(\mathbf{x})$

Computational examples

Solitons on lattice min

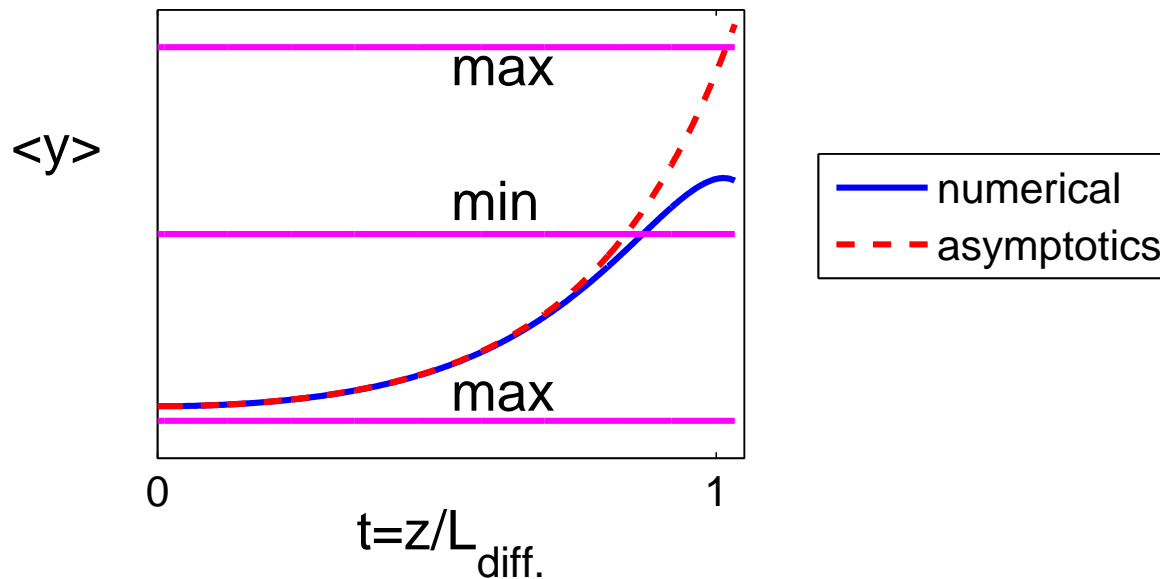
ψ_0 = soliton slightly shifted from lattice min



- solitons centered @ min are drift-stable
- center-of-mass dynamics matches asymptotics

Soliton on lattice max

ψ_0 = soliton slightly shifted from (2+1)D lattice max

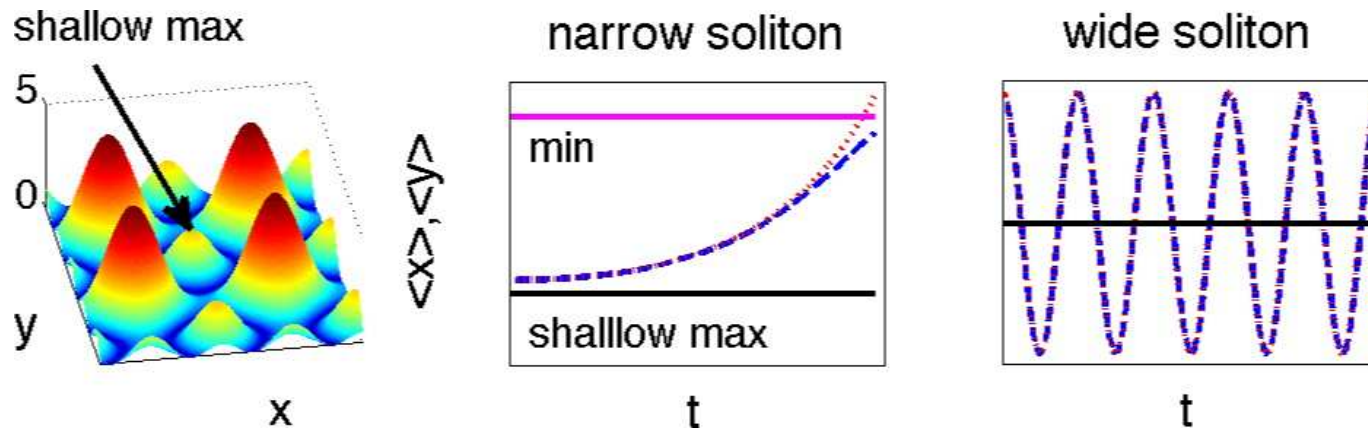


- solitons centered @ max are drift-unstable
- center-of-mass dynamics matches asymptotics

Soliton on shallow max

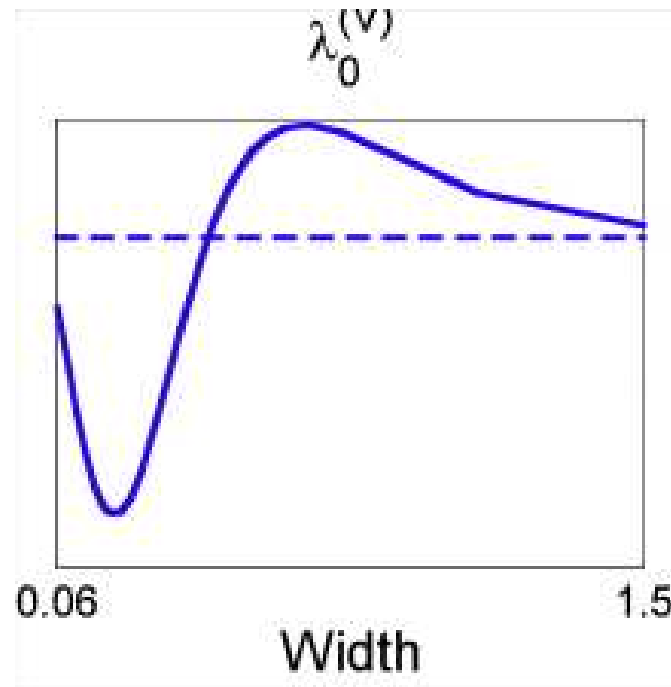
(2+1)D square lattice with shallow max

$$V(x, y) = 2.5 [1 + \cos(2\pi x) + \cos(2\pi y)]^2$$



- narrow soliton @ max \implies drift unstable
- wide soliton effectively @ min \implies drift stable
- $\lambda_0^{(i)}$ predict drift (in)stability

Shallow max – cont.



- $\lambda_0^{(i)}$ changes sign as soliton becomes wider

Conclusions

- Stability theory:
 - $V(\mathbf{x})$ can be extended, a-symmetric, any dimension
 - need power-slope & **spectral** conditions
- Instability dynamics:
 - Violation of power-slope condition \implies amplitude instability
 - Violation of spectral condition \implies drift instability
 - analytic formulae for drift/oscillations
 - $|\frac{dP}{dE}|, |\lambda_0^{(i)}|$ determine strength of (in)stabilities

Thank you for your attention!